## Lecture 17.4: Relational Representations

- Probabilistic Logic Programs
- Weighted Logical Formulae
- Graph Neural Networks
- Existence and Identity Uncertainty


## Probabilistic Logic Programs

- the model is described in terms of a logic program with parametrized independent noise variables.
- Plates correspond to logical variables.
- Parametrized random variables are represented as logical atoms,
- A Turing-complete language for relational probabilistic models.
- Extends Datalog / logic programs to include probabilities.


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\begin{aligned}
& \text { is_shot }(Y) \leftarrow \text { shot_by_no_one }(Y) \\
& \text { is_shot }(Y) \leftarrow \text { shot }(X, Y) \wedge \text { shot_succeeds }(X, Y)
\end{aligned}
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Each ground instance of shot_by_no_one $(Y)$ and shot_succeeds $(X, Y)$ are independent noise variables.

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$\operatorname{shot}(X, Y) \leftarrow$ has_motive $(X, Y) \wedge$ has_gun $(X)$
$\wedge$ has_opportunity $(X, Y) \wedge$ actually_shot $(X, Y)$.
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- Other rules could cover other cases, such as where $X$ doesn't have a motive.


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- In Markov logic networks (MLNs), the measure of a world is proportional to the exponential of the sum of the weights of the formulae true in the world.
- A conditional probability, $P(x \mid o b s)$ is the measure of the worlds in which $x$ is true out of the worlds in which obs is true.


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- In relational logistic regression, the weighted formulae are used to define conditional probabilities.


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MLNs provide an undirected model, e.g.,
(is_shot $\left.(Y), w_{0}\right)$
(is_shot $\left.(Y) \vee \neg \operatorname{shot}(X, Y), w_{1}\right)$
(shot $(X, Y) \vee \neg$ has_motive $(X, Y) \vee \neg$ has_gun $(X)$
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$P\left(\right.$ is_shot $\left.(v) \mid \operatorname{shot}\left(p_{1}, v\right), \ldots \operatorname{shot}\left(p_{n}, v\right)\right)$ is logistic regression if $p_{1}, \ldots, p_{n}$ are all the individuals.

## Graph Neural Networks

- Graph neural networks are neural networks that act on graph data.
- Each node has an embedding that is inferred from parametrized linear functions and activation functions of the node's neighbors, and their neighbors, to some depth.
- A relational graph convolutional network (R-GCN) is used to learn embeddings for knowledge graphs, where nodes are entities and arcs are labelled with relations.


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- Called convolutional because the same learnable parameters are used for each entity.


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- $R$ is the set of all relations
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- $W_{r}^{(L)}$ is a matrix for relation $r$ for layer $L$, which is multiplied by the vector $h_{n}^{(L)}$ for each neighbor $n$.
- $C_{e, r}$ is a normalization constant, such as $|\{n:(e, r, n) \in K G\}|$, which gives an average for each relation.


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- $W_{r}^{(L)}$, can be represented as a linear combination of a few learned basis matrices which are shared among the relations
- the weights in the linear combination depend on the relation.
- Question: Is summing or avaraging an appropriate way to aggegate the embeddings of related entities? Would something else be more appropriate?


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Assumed the set of entities is known.
- Identity uncertainty concerns uncertainty of whether two symbols denote the same entity - the symbols are equal
- Existence uncertainty concerns uncertainty as to whether there exists an entity that fits a description
- Number uncertainty concerns uncertainty as how many entities fit a description


## Existence and Identity Example



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- Huan's glasses $\neq$ Kiran's glasses, because they denote different pairs of glasses
- Milo's glasses do not exist; Milo doesn't have a pair of glasses.


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- The number of partitions of $n$ items is the Bell number, which grows faster than any exponential in $n$.
- Use Markov-chain Monte Carlo (MCMC): given a partition, entities can be moved to different partitions or to new partitions.


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