## Embedding Based Models – Lecture 17.2

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   E.g., predicting the rating for a person on a movie (collaborative filtering).
- Knowledge graphs: predict subject-verb-object triples.



### Learning a relation between two entities

A relation between users and items (movies). From Movielens:

User	Item	Rating	Timestamp
196	242	3	881250949
186	302	3	891717742
22	377	1	878887116
244	51	2	880606923

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 $\widehat{r_{ui}}$  = predicted rating of user u on item i Es = set of (u, i, r) tuples in the training set (ignoring timestamp) Minimize sum squares error:

$$\sum_{(u,i,r)\in Es} (\widehat{r_{ui}} - r)^2$$



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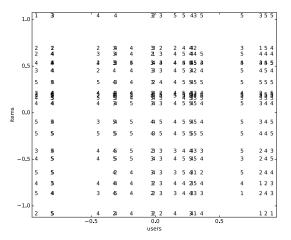
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- ► How do these clusterings interact?
- ► What about negative values?



## What is being learned? (Single latent feature)

for each (u, i, r): r is plotted at point  $(f_1[u], f_2[i])$ .

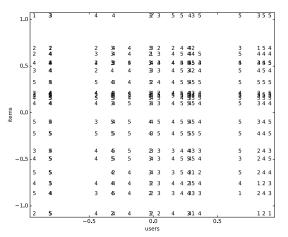


aipython: relnCollFilt.py



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aipython: relnCollFilt.py
What pattern would you expect?



• *k* latent features (Python notation):

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• Regularize parameters except  $\mu$ .



### Regularizing

• L2 regularization, minimize:

$$\left(\sum_{(u,i,r)\in Es} (\widehat{r_{ui}} - r)^2\right) + \lambda \sum_{parameter\ p} p^2$$



# L2 regularization

Minimize:

$$\left(\sum_{(u,i,r)\in Es} (\mu + b_1[u] + b_2[i] + \sum_k E_1[u][f] * E_2[i][f] - r)^2\right)$$

$$+ \lambda \left(\sum_i (b_1[u]^2 + \sum_f E_1[u][f]^2) + \sum_u (b_2[i]^2 + \sum_f E_2[i][f]^2)\right)$$

where  $\lambda$  is a regularization parameter.



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where  $\lambda$  is a regularization parameter.

To find minimizing parameters:

- Gradient descent
- Iterative least squares: fix one of  $E_1$  and  $E_2$ ; the problem is ridge regression in the other.



 $\mu:=$  average rating assign  $E_1[u][f]$ ,  $E_2[i][f]$  randomly and assign  $b_1[i]$ ,  $b_2[u]$  arbitrarily **repeat:** 

for each 
$$(u, i, r) \in Es$$
:  
 $e := \mu + b_1[i] + b_2[u] + \sum_k E_1[u][f] * E_2[i][f] - r$   
 $b_1[i] := b_1[i] - \eta * e$   
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 $E_1[u][f] := E_1[u][f] - \eta * e * E_2[i][f]$   
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8/14

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for each item i:

$$b_1[i] := b_1[i] - \eta * \lambda * b_1[i]$$

**for each** feature *f*:

$$E_1[u][f] := E_1[u][f] - \eta * \lambda * E_1[u][f]$$

for each user u:

$$b_2[u] := b_2[u] - \eta * \lambda * b_2[u]$$

**for each** feature k:

$$E_2[i][f] := E_2[i][f] - \eta * \lambda * E_2[i][f]$$

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  - ► There are no negative examples!
  - ▶ Use k random examples for each positive example! but the average probability is 1/k, which is not derived from the data.



## Knowledge Graphs and Triples

• A knowledge graph is defined in term of triples of the form (s, r, o), with subject s, relation (verb) r, and object s



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- The extension of matrix factorization to triples is polyadic decomposition:

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   E₁[e] is subject embedding for entity e



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All embeddings  $E_1[e]$ ,  $E_2[r]$  and  $E_3[e]$  are the same length.



• To optimize log loss with *L*2 regularization:



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- But, not all relations have same number of negative examples, eg. "married-to" vs "has-streamed".

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- polyadic decomposition with inverses:

$$\widehat{p}(h,r,t) = \frac{1}{2}(\widehat{pd}(h,r,t) + \widehat{pd}(t,r^{-1},h))$$

where  $\widehat{pd}$  is the prediction from the polyadic decomposition.



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- The addition lets these values be combined.



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- It learns about each entity; embeddings are used to predict interactions.
- It does not learn general knowledge that can be applied to other populations.