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- A substitution is a finite set of the form $\{V_1/t_1, \ldots, V_n/t_n\}$, where each V_i is a distinct variable and each t_i is a term.
- The application of a substitution $\sigma = \{V_1/t_1, \dots, V_n/t_n\}$ to an atom or clause *e*, written $e\sigma$, is the instance of *e* with every occurrence of V_i replaced by t_i .

$$\sigma_1 = \{X/A, Y/b, Z/C, D/e\}$$

$$\sigma_2 = \{A/X, Y/b, C/Z, D/e\}$$

$$\sigma_3 = \{A/V, X/V, Y/b, C/W, Z/W, D/e\}$$

The following shows some applications:

$$p(A, b, C, D)\sigma_{1} = p(X, Y, Z, e)\sigma_{1} = p(A, b, C, D)\sigma_{2} = p(X, Y, Z, e)\sigma_{2} = p(A, b, C, D)\sigma_{3} = p(X, Y, Z, e)\sigma_{3} =$$

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Given the substitution:

$$\sigma = \{X/A, Y/b, Z/C, D/e\}$$

foo(D, Z, C, A) σ is
A foo(D, Z, C, A)
B foo(e, C, C, A)
C foo(D, C, C, X)
D foo(e, C, C, X)
E foo(e, C, Z, A)

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Given the substitution:

 $\sigma = \{X/A, Y/b, Z/C, D/e\}$ foo(W, b, C, A) σ is A foo(X, Y, Z, D) B foo(b, b, C, Y) C foo(W, Y, C, X) D foo(W, b, C, A) E foo(W, Y, C, A)

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 - if substitution σ' also unifies e₁ and e₂, then eσ' is an instance of eσ for all atoms e.
- If two atoms have a unifier, they have a most general unifier.
- If there are multiple most general unifiers, they only differ in the names of the variables.

A yes B no C l'm not sure Is the substitution a unifier of p(A, b, C, D) and p(X, Y, Z, e): $\sigma_1 = \{X/A, Y/b, Z/C, D/e\}$ A yes B no C I'm not sure Is the substitution a unifier of p(A, b, C, D) and p(X, Y, Z, e): $\sigma_1 = \{X/A, Y/b, Z/C, D/e\}$ yes $\sigma_2 = \{Y/b, D/e\}$

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A yes

$$\sigma_3 = \{X/A, Y/b, Z/C, D/e, W/a\}$$
 yes

$$\sigma_4 = \{A/X, Y/b, C/Z, D/e\}$$
 yes

$$\sigma_5 = \{X/a, Y/b, Z/c, D/e\}$$
 no

$$\sigma_6 = \{A/a, X/a, Y/b, C/c, Z/c, D/e\}$$

B no C l'm not sure

A yes

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 yes

$$\sigma_5 = \{X/a, Y/b, Z/c, D/e\}$$
no

$$\sigma_6 = \{A/a, X/a, Y/b, C/c, Z/c, D/e\}$$
 yes

$$\sigma_7 = \{A/V, X/V, Y/b, C/W, Z/W, D/e\}$$

B no C l'm not sure

A yes

Is the substitution a unifier of p(A, b, C, D) and p(X, Y, Z, e):

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$$\sigma_{7} = \{A/V, X/V, Y/b, C/W, Z/W, D/e\}$$
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$$\sigma_{8} = \{X/A, Y/b, Z/A, C/A, D/e\}$$

B no C I'm not sure Is the substitution a unifier of p(A, b, C, D) and p(X, Y, Z, e): VDC

A yes

$$\sigma_1 = \{Y/b, D/e\}$$
 yes $\sigma_2 = \{Y/b, D/e\}$ no

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$$\sigma_8 = \{X/A, Y/b, Z/A, C/A, D/e\}$$
 yes

Which are most general unifiers?

 $\sigma_1 = \int X / A V / h Z / C D / a$

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A yes

$$\sigma_5 = \{X/a, Y/b, Z/c, D/e\}$$
 no

$$\sigma_6 = \{A/a, X/a, Y/b, C/c, Z/c, D/e\}$$
 yes

$$\sigma_7 = \{A/V, X/V, Y/b, C/W, Z/W, D/e\}$$
 yes

$$\sigma_8 = \{X/A, Y/b, Z/A, C/A, D/e\}$$
 yes

Which are most general unifiers? σ_1, σ_4

- 1: procedure $unify(t_1, t_2)$
- 2: $E := \{t_1 = t_2\}$
- 3: $S := \{\}$
- 4: while $E \neq \{\}$ do

▷ Returns mgu of t₁ and t₂ or ⊥.
 ▷ Set of equality statements
 ▷ Substitution

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- 1: procedure $unify(t_1, t_2)$
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- 5: select and remove x = y from *E*

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1: procedure $unify(t_1, t_2)$ \triangleright Returns mgu of t_1 and t_2 or \bot . 2: $E := \{t_1 = t_2\}$ \triangleright Set of equality statements 3: $S := \{\}$ \triangleright Substitution 4: while $E \neq \{\}$ do 5: select and remove x = y from E

6: **if** y is not identical to x **then**

1: procedure $unify(t_1, t_2)$ \triangleright Returns mgu of t_1 and t_2 or \perp . $E := \{t_1 = t_2\}$ ▷ Set of equality statements 2: $S := \{\}$ 3: Substitution while $E \neq \{\}$ do 4: 5: select and remove x = y from E if y is not identical to x then 6: if x is a variable then 7: 8: replace x with y in E and S $S := \{x/y\} \cup S$ 9:

1: pr	rocedure $unify(t_1, t_2)$	\triangleright Returns mgu of t_1 and t_2 or \perp .
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4:	while $E \neq \{\}$ do	
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6:	if y is not identical to x then	
7:	if x is a variable then	
8:	replace x with y in E and S	
9:	$S := \{x/y\}$ (J S
10:	else if y is a var	riable then
11:	replace y wit	h x in E and S
12:	$S := \{y/x\}$ (J S

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13:	else if x is $p(x_1,$	\ldots, x_n) and y is $p(y_1, \ldots, y_n)$ then	
14:	$E := E \cup \{x_1$	$1 = y_1, \ldots, x_n = y_n\}$	

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4:	while $E \neq \{\}$ do		
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15:	else		
16:	return ot	\triangleright t_1 and t_2 do not unify	
17:	return S	$\triangleright S$ is mgu of t_1 and t_2	

• unify p(A, b, C, D) and p(X, Y, Z, e)

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• unify p(A, b, C, D) and p(X, Y, Z, e) $\{A/X, Y/b, C/Z, D/e\}$

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- unify p(A, b, A, d) and p(X, X, Z, Z) \perp
- unify n([sam, likes, prolog], L2, I, C1, C2) and n([P|R], R, P, [person(P)|C], C)

- unify p(A, b, C, D) and p(X, Y, Z, e) $\{A/X, Y/b, C/Z, D/e\}$
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- unify p(A, b, A, d) and p(X, X, Z, Z) \perp
- unify n([sam, likes, prolog], L2, I, C1, C2) and n([P|R], R, P, [person(P)|C], C) {P/sam, R/[likes, prolog], L2/[likes, prolog], I/sam, C1/[person(sam)|C2], C/C2}

Atom g is a logical consequence of KB if and only if:

- g is an instance of a fact in KB, or
- there is an instance of a rule

 $g \leftarrow b_1 \land \ldots \land b_k$

in KB such that each b_i is a logical consequence of KB.

To debug answer g that is false in the intended interpretation:

- If g is a fact in KB, this fact is wrong.
- Otherwise, suppose g was proved using the rule:

 $g \leftarrow b_1 \land \ldots \land b_k$

where each b_i is a logical consequence of KB.

- If each b_i is true in the intended interpretation, this clause is false in the intended interpretation.
- ▶ If some *b_i* is false in the intended interpretation, debug *b_i*.

- A proof is a mechanically derivable demonstration that a formula logically follows from a knowledge base.
- Given a proof procedure, KB ⊢ g means g can be derived from knowledge base KB.
- Recall $KB \models g$ means g is true in all models of KB.
- A proof procedure is sound if $KB \vdash g$ implies $KB \models g$.
- A proof procedure is complete if $KB \models g$ implies $KB \vdash g$.

 $\begin{array}{l} \mathcal{KB} \vdash g \text{ if there is } g' \text{ added to } C \text{ in this procedure where } g = g'\theta \text{:} \\ \mathcal{C} := \{\}; \\ \textbf{repeat} \\ \textbf{select clause } ``h \leftarrow b_1 \land \ldots \land b_m" \text{ in } \mathcal{KB} \text{ such that} \\ \text{ there is a substitution } \theta \text{ such that} \\ \text{ for all } i, \text{ there exists } b'_i \in C \text{ and } \theta'_i \text{ where } b_i\theta = b'_i\theta'_i \text{ and} \\ \text{ there is no } h' \in C \text{ and } \theta' \text{ such that } h'\theta' = h\theta \\ \mathcal{C} := \mathcal{C} \cup \{h\theta\} \end{array}$

until no more clauses can be selected.

$live(Y) \leftarrow connected_to(Y, Z) \land live(Z).$ live(outside). $connected_to(w_6, w_5).$ $connected_to(w_5, outside).$

$$\begin{split} & live(Y) \leftarrow connected_to(Y,Z) \land live(Z). \ live(outside). \\ & connected_to(w_6,w_5). \quad connected_to(w_5,outside). \\ & C = \{live(outside), \\ & connected_to(w_6,w_5), \\ & connected_to(w_5,outside), \\ & live(w_5), \\ & live(w_6)\} \end{split}$$

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If $KB \vdash g$ then $KB \models g$.

- Suppose there is a g such that $KB \vdash g$ and $KB \not\models g$.
- Then there must be a first atom added to C that has an instance that isn't true in every model of KB. Call it h.

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- Suppose h isn't true in model I of KB.
- There must be an instance of clause in KB of form

$$h' \leftarrow b_1 \land \ldots \land b_m$$

where

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where $h = h'\theta$ and $b_i\theta$ is an instance of an element of C.

- Each $b_i \theta$ is true in *I*.
- h is false in I.
- So an instance of this clause is false in *I*.
- Therefore I isn't a model of KB.
- Contradiction.

- The *C* generated by the bottom-up algorithm is called a fixed point.
- C can be infinite; we require the selection to be fair.
- Herbrand interpretation: The domain is the set of constants. We invent a constant if the KB or query doesn't contain one. Each constant denotes itself.

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- Let *I* be the Herbrand interpretation in which every ground instance of every element of the fixed point is true and every other atom is false.

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- Herbrand interpretation: The domain is the set of constants. We invent a constant if the KB or query doesn't contain one. Each constant denotes itself.
- Let *I* be the Herbrand interpretation in which every ground instance of every element of the fixed point is true and every other atom is false.
- *I* is a model of *KB*. Proof:

- The *C* generated by the bottom-up algorithm is called a fixed point.
- C can be infinite; we require the selection to be fair.
- Herbrand interpretation: The domain is the set of constants. We invent a constant if the KB or query doesn't contain one. Each constant denotes itself.
- Let *I* be the Herbrand interpretation in which every ground instance of every element of the fixed point is true and every other atom is false.
- *I* is a model of *KB*.
 Proof: suppose *h* ← *b*₁ ∧ ... ∧ *b_m* in *KB* is false in *I*. Then *h* is false and each *b_i* is true in *I*. Thus *h* can be added to *C*. Contradiction to *C* being the fixed point.
- *I* is called a Minimal Model.

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 Consider "this statement cannot be proved".

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Prolog can represent this, and so cannot be both sound and complete.

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• The (SLD) resolution of this answer clause on atom *a*₁ with the clause in the knowledge base:

$$a_1 \leftarrow b_1 \land \ldots \land b_p$$

is the answer clause

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A fact in the knowledge base is considered as a clause where p = 0.

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• A generalized answer clause is of the form

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where a_1 and a have most general unifier θ , is

$$(yes(t_1,\ldots,t_k) \leftarrow b_1 \land \ldots \land b_p \land a_2 \land \ldots \land a_m) \theta$$

To solve the query $?q_1 \land \ldots \land q_k$:

$$ac := "yes \leftarrow q_1 \land \ldots \land q_k"$$

repeat

select atom a1 from the body of ac
choose clause C from KB with a1 as head
replace a1 in the body of ac by the body of C
until ac is an answer.

Set *ac* to generalized answer clause $yes(V_1, \ldots, V_k) \leftarrow B$

Set *ac* to generalized answer clause $yes(V_1, \ldots, V_k) \leftarrow B$ while *ac* is not an answer **do**

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Suppose *ac* is generalized answer clause $yes(t_1, ..., t_k) \leftarrow$ Answer is $V_1 = t_1, ..., V_k = t_k$

 $live(Y) \leftarrow connected_to(Y, Z) \land live(Z).$ live(outside). $connected_to(w_6, w_5).$ $connected_to(w_5, outside).$?live(A). $yes(A) \leftarrow live(A).$

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elem(V, set(E,LT,_)) :-
    V #< E,
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elem(V, set(E,_,RT)) :-
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?- elem(3,S),elem(8,S).</pre>
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What is the resolution of the generalized answer clause:

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yes(B, N) \leftarrow append(B, [a, N|R], [b, a, c, d]).
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with the clause

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- In an interpretation and with a variable assignment, term $f(t_1, \ldots, t_n)$ denotes an individual in the domain.
- One function symbol and one constant can refer to infinitely many individuals.

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append(X, Y, Z) is true if list Z contains the elements of X followed by the elements of Y append(nil, Z, Z).
 append(cons(A, X), Y, cons(A, Z)) ← append(X, Y, Z).

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- What does the top-down proof procedure give?
- Solution: variable X should not unify with a term that contains X inside. "Occurs check"
 E.g., X should not unify with s(X).
 Simple modification of the unification algorithm, which Prolog does not do!