

# Single agent or multiple agents

- Many domains are characterized by multiple agents rather than a single agent.
- **Game theory** studies what agents should do in a multi-agent setting. A **game** is an abstraction of agents interacting.
- Agents can be cooperative, competitive or somewhere in between.
- Agents that reason and act autonomously can't be modeled as nature.

# Multi-agent framework

- Each agent can have its own utility.
- Agents select actions autonomously.
- Agents can have different information.
- The outcome can depend on the actions of all of the agents.
- Each agent's value depends on the outcome.

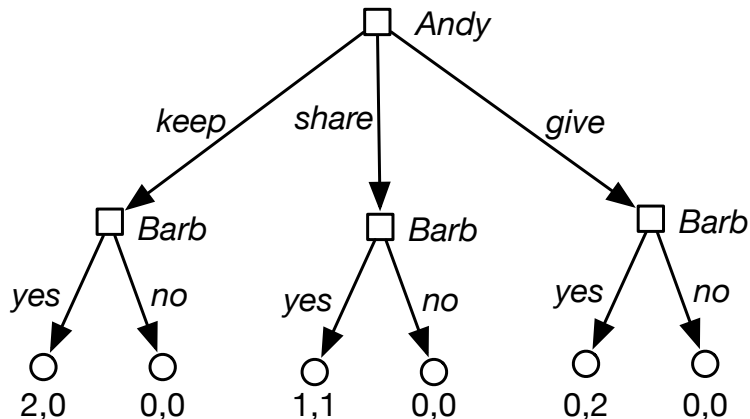
The **strategic form of a game** or **normal-form game**:

- a finite set  $I$  of agents,  $\{1, \dots, n\}$ .
- a set of actions  $A_i$  for each agent  $i \in I$ .  
An **action profile**  $\sigma$  is a tuple  $\langle a_1, \dots, a_n \rangle$ , means agent  $i$  carries out  $a_i$ .
- a utility function  $utility(\sigma, i)$  for action profile  $\sigma$  and agent  $i \in I$ , gives the expected utility for agent  $i$  when all agents follow action profile  $\sigma$ .

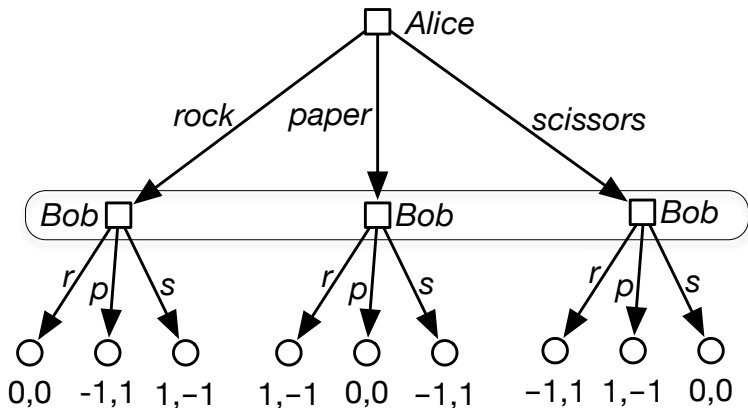
# Rock-Paper-Scissors

|       |                 | Bob         |              |                 |
|-------|-----------------|-------------|--------------|-----------------|
|       |                 | <i>rock</i> | <i>paper</i> | <i>scissors</i> |
| Alice | <i>rock</i>     | 0, 0        | -1, 1        | 1, -1           |
|       | <i>paper</i>    | 1, -1       | 0, 0         | -1, 1           |
|       | <i>scissors</i> | -1, 1       | 1, -1        | 0, 0            |

# Extensive Form of a Game

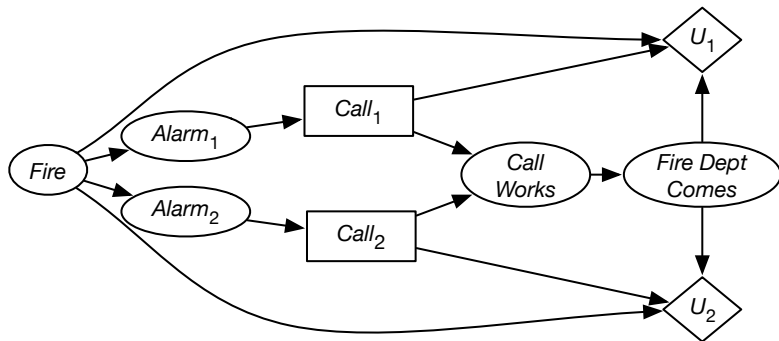


# Extensive Form of an imperfect-information Game



Bob cannot distinguish the nodes in an **information set**.

# Multiagent Decision Networks

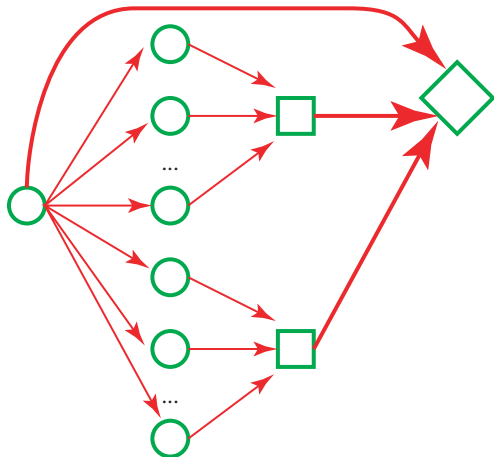


Value node for each agent.

Each decision node is owned by an agent.

The parents of each decision node specify what that agent will observe when making the decision

# Multiple Agents, shared value





# Complexity of Multi-agent decision theory

- It can be exponentially harder to find optimal multi-agent policy even with a shared values.
- **Why?** Because dynamic programming doesn't work:
  - ▶ If a decision node has  $n$  binary parents, dynamic programming lets us solve  $2^n$  decision problems.
  - ▶ This is much better than  $d^{2^n}$  policies (where  $d$  is the number of decision alternatives).
- Multiple agents with shared values is equivalent to having a single forgetful agent.