

# Model Averaging (Bayesian Learning)

We want to predict the output  $Y$  of a new case that has input  $X = x$  given the training examples  $Es$ :

$$\begin{aligned} p(Y | x \wedge Es) &= \sum_{m \in M} P(Y \wedge m | x \wedge Es) \\ &= \sum_{m \in M} P(Y | m \wedge x \wedge Es)P(m | x \wedge Es) \\ &= \sum_{m \in M} P(Y | m \wedge x)P(m | Es) \end{aligned}$$

$M$  is a set of mutually exclusive and covering models (hypotheses).

- What assumptions are made here?

- The posterior probability of a model  $m$  given training examples  $Es$ :

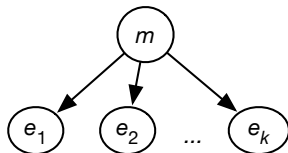
$$P(m | Es) = \frac{P(Es | m) \times P(m)}{P(Es)}$$

- The **likelihood**,  $P(Es | m)$ , is the probability that model  $m$  would have produced examples  $Es$ .
- The **prior**,  $P(m)$ , encodes a **learning bias**
- $P(Es)$  is a normalizing constant so the probabilities of the models sum to 1.
- You could try to fit the training data as well as possible by picking the **maximum likelihood model**, but that overfits.

# Independent and Identically Distributed

- Examples  $E_s = [e_1, \dots, e_k]$  are **independent and identically distributed (i.i.d.)** given model  $m$  if

$$P(E_s | m) = \prod_{i=1}^k P(e_i | m)$$



- Conditioning on the observed  $e_i$  and querying an unobserved  $e_j$  provides a probabilistic prediction for unseen examples.
- Conditioning on the observed  $e_i$  and querying  $m$  provides a distribution over models.

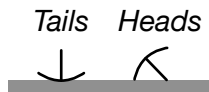
# Learning probabilities — the simplest case

Observe tosses of thumbtack:

$n_0$  instances of *Heads* = *false*

$n_1$  instances of *Heads* = *true*

what should we use as  $P(\textit{heads})$ ?



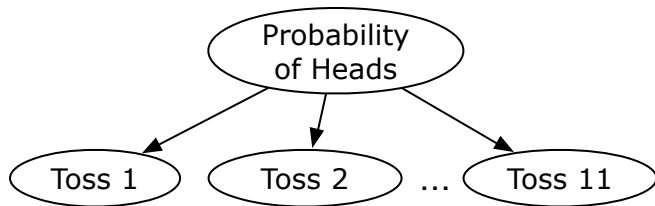
- Empirical frequency:  $P(\textit{heads}) = \frac{n_1}{n_0 + n_1}$
- Laplace smoothing [1812]:  $P(\textit{heads}) = \frac{n_1 + 1}{n_0 + n_1 + 2}$
- Informed priors:  $P(\textit{heads}) = \frac{n_1 + c_1}{n_0 + n_1 + c_0 + c_1}$   
for some informed **pseudo counts**  $c_0, c_1 > 0$ .  
 $c_0 = 1, c_1 = 1$ , expressed ignorance (uniform prior)

Pseudo-counts convey prior knowledge. Consider: “how much more would I believe  $\alpha$  if I had seen one example with  $\alpha$  true than if I has seen no examples with  $\alpha$  true?”

— empirical frequency overfits to the data.

# Example of Overfitting

- Consider a web site where people rate restaurants with 1 to 5 stars.
- We want to report the most liked restaurant(s) — the one predicted to have the best future ratings.
- How can we determine the most liked restaurant?
- Are the restaurants with the highest average rating the most liked restaurants?
- Which restaurants have the highest average rating?
- Which restaurants have a rating of 5?
  - ▶ Only restaurants with few ratings have an average rating of 5.
- Solution: add some “average” ratings for each restaurant!



aipython.org: coinTossBN in learnBayesian.py

- *Probability\_of\_Heads* is a random variable representing the probability of heads.
- Domain is  $\{0.0, 0.1, 0.2, \dots, 0.9, 1.0\}$  or interval  $[0, 1]$ .
- $P(\text{Toss}\#n=\text{Heads} \mid \text{Probability\_of\_Heads}=v) = v$
- *Toss#i* is independent of *Toss#j* (for  $i \neq j$ ) given *Probability\_of\_Heads*
- **i.i.d.** or **independent and identically distributed**.

# Bayesian Learning of Probabilities

- $Y$  has two outcomes  $y$  and  $\neg y$ .

We want the probability of  $y$  given training examples  $E_s$ .

- Treat the probability of  $y$  as a real-valued random variable on the interval  $[0, 1]$ , called  $\phi$ . Bayes' rule gives:

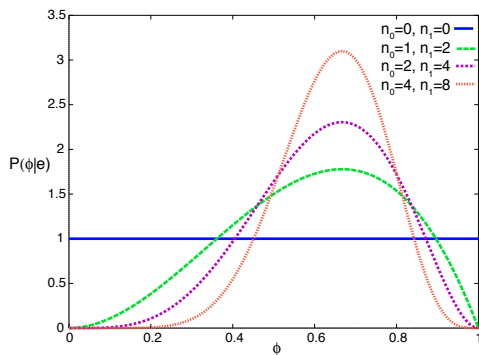
$$P(\phi=p \mid E_s) = \frac{P(E_s \mid \phi=p) \times P(\phi=p)}{P(E_s)}$$

- Suppose  $E_s$  is a sequence of  $n_1$  instances of  $y$  and  $n_0$  instances of  $\neg y$ :

$$P(E_s \mid \phi=p) = p^{n_1} \times (1 - p)^{n_0}$$

- Uniform prior:  $P(\phi=p) = 1$  for all  $p \in [0, 1]$ .

# Posterior Probabilities for Different Training Examples (beta distribution)



AIPython.org see probBeta.py

- The mode is the empirical average.
- The expected value is Laplace smoothing (pseudo-count of 1).



$$\text{Beta}^{\alpha_0, \alpha_1}(p) = \frac{1}{K} p^{\alpha_1 - 1} \times (1 - p)^{\alpha_0 - 1}$$

where  $K$  is a normalizing constant.  $\alpha_i > 0$ .

- The uniform distribution on  $[0, 1]$  is  $\text{Beta}^{1,1}$ .
- The expected value is  $\alpha_1 / (\alpha_0 + \alpha_1)$ .
- If the prior probability of a Boolean variable is  $\text{Beta}^{\alpha_0, \alpha_1}$ , the posterior distribution after observing  $n_1$  true cases and  $n_0$  false cases is:

$$\text{Beta}^{\alpha_0 + n_0, \alpha_1 + n_1}$$

- If the prior is of the form of a beta distribution, so is the posterior — called a **conjugate distribution**.

# Categorical Variables

- Suppose  $Y$  is a **categorical variable** with  $k$  possible values.
- A distribution over a categorical variable is called a **multinomial distribution**.
- The **Dirichlet distribution** is the generalization of the beta distribution to cover categorical variables.
- A **Dirichlet distribution** has form:

$$\text{Dirichlet}^{\alpha_1, \dots, \alpha_k}(p_1, \dots, p_k) = \frac{\prod_{j=1}^k p_j^{\alpha_j - 1}}{Z}$$

where

- ▶  $p_i$  is the probability of the  $i$ th outcome (and so  $0 \leq p_i \leq 1$ )
- ▶  $\alpha_i$  is a positive real number (a “count”)
- ▶  $Z$  is a normalizing constant that ensures the integral over all the probability values is 1.

# Probabilities from Experts

Problems with using probabilities from experts for cases with little data or poor data – e.g., medical diagnosis from health records:

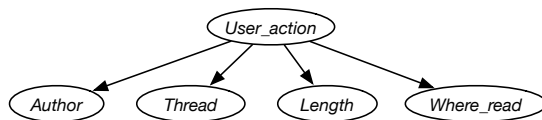
- experts are reluctant to give a precise number
- representing the uncertainty of a probability estimate
- combining the estimates from multiple experts
- combining expert opinion with actual data.

Instead of giving a real number for the probability of proposition  $\alpha$ , an expert gives a pair  $\langle n, m \rangle$  of numbers, interpreted as though the expert had observed  $n$  occurrences of  $\alpha$  out of  $m$  trials.

- the numbers from different experts can be added
- the number can be combined with real data
- the effective sample size ( $m$ ) can be tuned to reflect expertise.

# Probabilistic Classifiers

- A **Bayes classifier** is a probabilistic model that is used for supervised learning.
- idea: the role of a **class** is to predict the values of features for members of that class.
- In a **naive Bayes classifier** the input features are conditionally independent of each other given the classification.  
Example: Suppose an agent wants to predict the user action based on properties of an online discussion:



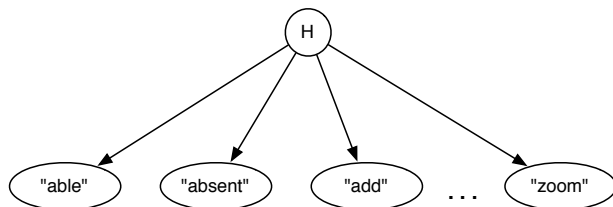
# Naive Bayes Classifiers

With inputs  $X_1=v_1, \dots, X_k=v_k$ , and classification,  $Y$ :

$$\begin{aligned} P(y \mid X_1=v_1, \dots, X_k=v_k) &= \frac{P(y) * \prod_{i=1}^k P(X_i=v_i \mid y)}{P(y) * \prod_{i=1}^k P(X_i=v_i \mid y) + P(\neg y) * \prod_{i=1}^k P(X_i=v_i \mid \neg y)} \\ &= \frac{1}{1 + \frac{P(\neg y) * \prod_{i=1}^k P(X_i=v_i \mid \neg y)}{P(y) * \prod_{i=1}^k P(X_i=v_i \mid y)}} \\ &= \frac{1}{1 - \exp(\log(\frac{P(\neg y) * \prod_{i=1}^k P(X_i=v_i \mid \neg y)}{P(y) * \prod_{i=1}^k P(X_i=v_i \mid y)}))} \\ &= \text{sigmoid} \left( \log\left(\frac{P(y)}{P(\neg y)}\right) + \sum_i \log\left(\frac{P(X_i=v_i \mid y)}{P(X_i=v_i \mid \neg y)}\right) \right) \end{aligned}$$

is a Logistic regression model when all  $X_j$  are observed

# Naive Bayes Classifier: User's request for help



$H$  is the help page the user is interested in.

We observe the words in the query.

What probabilities are required?

What counts are required?

- number of times each help page  $h_i$  is the best one
- number of times word  $w_j$  is used when  $h_i$  is the help page.

When can the counts be updated?

- When the correct page is found.

What prior counts should be used? Can they be zero?

- Suppose the help pages are  $\{h_1, \dots, h_k\}$ .
- Words are  $\{w_1, \dots, w_m\}$ .
- Bayes net requires:
  - ▶  $P(h_i)$ , these sum to 1 ( $\sum_i P(h_i) = 1$ )
  - ▶  $P(w_j | h_i)$ , do not sum to one in a set-of-words model
- Maintain “counts” (pseudo counts + observed cases):
  - ▶  $c_i$  the number of times  $h_i$  was the correct help page
  - ▶  $s = \sum_i c_i$
  - ▶  $u_{ij}$  the number of times  $h_i$  was the correct help page and word  $w_j$  was used in the query.
- $P(h_i) = c_i/s$
- $P(w_j | h_i) = u_{ij}/c_i$

- $Q$  is the set of words in the query.
- Learning: if  $h_i$  is the correct page: Increment  $s$ ,  $c_i$  and  $u_{ij}$  for each  $w_j \in Q$ .
- Inference:

$$\begin{aligned}
 P(h_i | Q) &\propto P(h_i) \prod_{w_j \in Q} P(w_j | h_i) \prod_{w_j \notin Q} (1 - P(w_j | h_i)) \\
 \left. \begin{array}{l} \text{expensive} \\ \text{inference} \end{array} \right\} &= \frac{c_i}{s} \prod_{w_j \in Q} \frac{u_{ij}}{c_i} \prod_{w_j \notin Q} \frac{c_i - u_{ij}}{c_i} \\
 &= \frac{c_i}{s} \prod_{w_j} \frac{c_i - u_{ij}}{c_i} \prod_{w_j \in Q} \frac{u_{ij}}{c_i - u_{ij}} \\
 \left. \begin{array}{l} \text{expensive} \\ \text{learning} \end{array} \right\} &= \psi_i \prod_{w_j \in Q} \frac{u_{ij}}{c_i - u_{ij}}
 \end{aligned}$$



If you were designing such a system, many issues arise such as:

- What if the most likely page isn't the correct page?
- What if the user can't find the correct page?
- What if the user mistakenly thinks they have the correct page?
- Can some pages never be found?
- What about common words?
- What about words that affect other words, e.g. "not"?
- What about new words?
- What do we do with new help pages?
- How can we transfer the language model to a new help system?