### Learning Objectives

At the end of the class you should be able to:

- identify a supervised learning problem
- characterize how the prediction is a function of the error measure
- avoid mixing the training and test sets



## Supervised Learning

#### Given:

- a set of inputs features  $X_1, \ldots, X_n$
- a set of target features  $Y_1, \ldots, Y_k$
- a set of training examples where the values for the input features and the target features are given for each example
- a new example, where only the values for the input features are given

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- $\bullet$  classification when the  $Y_i$  are discrete
- regression when the  $Y_i$  are continuous



### Example Data Representations

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Two representations of the same data:

- *Y* is the length of trip chosen.
- Each  $Y_i$  is an indicator variable that has value 1 if the chosen length is i, and is 0 otherwise.

Example	Y	Example	$Y_1$	$Y_2$	$Y_3$	$Y_4$	$Y_5$	$Y_6$
$e_1$	1	$e_1$	1	0	0	0	0	0
$e_2$	6	$e_2$	0	0	0	0	0	1
$e_3$	6	<i>e</i> <sub>3</sub>	0	0	0	0	0	1
$e_4$	2	<i>e</i> <sub>4</sub>	0	1	0	0	0	0
$e_5$	1	$e_5$	1	0	0	0	0	0

What is a prediction?

Suppose we want to make a prediction of a value for a target feature on example *e*:

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- $\bullet$   $o_e$  is the observed value of target feature on example e.
- $p_e$  is the predicted value of target feature on example e.
- The error of the prediction is a measure of how close  $p_e$  is to  $o_e$ .
- There are many possible errors that could be measured.

Sometimes  $p_e$  can be a real number even though  $o_e$  can only have a few values.



*E* is a sequence of examples, with single target feature. For  $e \in E$ ,  $o_e$  is observed value and  $p_e$  is predicted value:

• absolute error  $L_1(E) = \sum_{e \in E} |o_e - p_e|$ 

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- A cost-based error takes into account costs of errors.



# Measures of error (cont.)

With binary feature:  $o_e \in \{0, 1\}$ :

likelihood of the data

$$\prod_{e\in E} p_e^{o_e} (1-p_e)^{(1-o_e)}$$

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in terms of information:



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in terms of information:

It is negative of number of bits to encode the data given a code based on  $p_e$ .



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- Can we do better?

Consider a code to distinguish elements of  $\{a, b, c, d\}$  with

$$P(a) = \frac{1}{2}, P(b) = \frac{1}{4}, P(c) = \frac{1}{8}, P(d) = \frac{1}{8}$$

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Consider the code:

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=  $\frac{1}{2} + \frac{2}{4} + \frac{3}{8} + \frac{3}{8} = 1\frac{3}{4}$  bits.

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The code 0111110010100 represents string adcabba



#### Information Content

- To identify x, we need  $-\log_2 P(x)$  bits.
- Give a distribution over a set, to a identify a member, the expected number of bits

$$\sum_{x} -P(x) \times \log_2 P(x).$$

is the information content or entropy of the distribution.

 The expected number of bits it takes to describe a distribution given evidence e:

$$I(e) = \sum_{x} -P(x|e) \times \log_2 P(x|e).$$



#### Information Gain

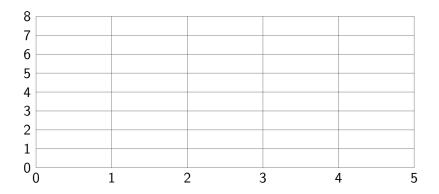
Given a test that can distinguish the cases where  $\alpha$  is true from the cases where  $\alpha$  is false, the information gain from this test is:

$$I(true) - (P(\alpha) \times I(\alpha) + P(\neg \alpha) \times I(\neg \alpha)).$$

- I(true) is the expected number of bits needed before the test
- $P(\alpha) \times I(\alpha) + P(\neg \alpha) \times I(\neg \alpha)$  is the expected number of bits after the test.

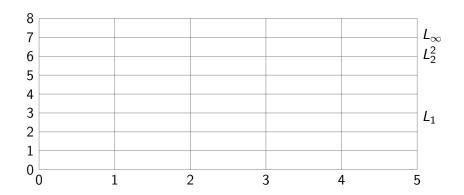


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Predict single value for numerical feature Y on examples E.

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But that doesn't mean that these predictions minimize the error for future predictions....



### Training and Test Sets

To evaluate how well a learner will work on future predictions, we divide the examples into:

- training examples that are used to train the learner
- test examples that are used to evaluate the learner

...these must be kept separate.