At the end of the class you should be able to:

- Explain the components and the architecture of a learning problem
- Explain why a learner needs a bias
- Identify the sources of error for a prediction

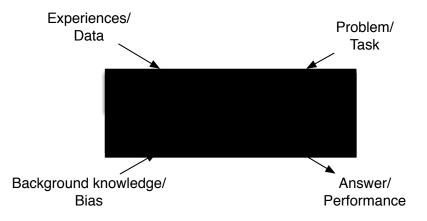
Learning is the ability to improve one's behavior based on experience.

- The range of behaviors is expanded: the agent can do more.
- The accuracy on tasks is improved: the agent can do things better.
- The speed is improved: the agent can do things faster.

The following components are part of any learning problem:

- task The behavior or task that's being improved. For example: classification, acting in an environment
- data The experiences that are being used to improve performance in the task.
- measure of improvement How can the improvement be measured?

For example: increasing accuracy in prediction, new skills that were not present initially, improved speed.



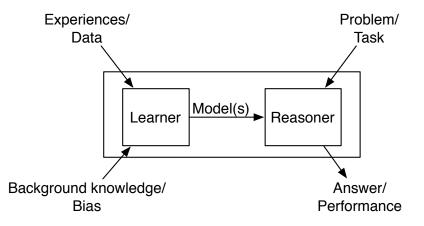


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- Inductive logic programming Build richer models in terms of logic programs.
- Statistical relational learning learning relational representations that also deal with uncertainty.

Training Examples:

| | Action | Author | Thread | Length | Where |
|---------------|--------|---------|--------|--------|-------|
| e1 | skips | known | new | long | home |
| e2 | reads | unknown | new | short | work |
| e3 | skips | unknown | old | long | work |
| e4 | skips | known | old | long | home |
| e5 | reads | known | new | short | home |
| e6 | skips | known | old | long | work |
| New Examples: | | | | | |
| e7 | ??? | known | new | short | work |
| e8 | ??? | unknown | new | short | work |

We want to classify new examples on feature *Action* based on the examples' *Author*, *Thread*, *Length*, and *Where*.

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- Supervised learning What has to be learned is specified for each example.
- Unsupervised learning No classifications are given; the learner has to discover categories and regularities in the data.
- Reinforcement learning Feedback occurs after a sequence of actions.

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- Consider two agents:
 - P claims the negative examples seen are the only negative examples. Every other instance is positive.
 - N claims the positive examples seen are the only positive examples. Every other instance is negative.
- Both agents correctly classify every training example, but disagree on every other example.

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- Saying a hypothesis is better than N's or P's hypothesis isn't something that's obtained from the data.
- To have any inductive process make predictions on unseen data, an agent needs a bias.
- What constitutes a good bias is an empirical question about which biases work best in practice.

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- Learning is search through the space of possible representations looking for the representation or representations that best fits the data, given the bias.
- These search spaces are typically prohibitively large for systematic search. E.g., use gradient descent or stochastic simulation.
- A learning algorithm is made of a search space, an evaluation function, and a search method.

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- the features given are inadequate to predict the classification
- there are examples with missing features
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- overfitting occurs when distinctions appear in the training data, but not in the unseen examples.

• Limited representation (representation bias)

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- Limited search (search bias)
- Limited data (variance)
- Limited features (noise)

• The richer the representation, the more useful it is for subsequent problem solving.

• The richer the representation, the more difficult it is to learn. "bias-variance tradeoff"

- Find the best model given the data.
- Delineate the class of consistent models given the data.
- Find a probability distribution of the models given the data.